

Source	$D \rightarrow$	$\mathcal{A}(B^\pm \rightarrow DX_d^\pm)$		$\mathcal{A}(B^\pm \rightarrow DX_s^\pm)$		R_{CP+}		R_d^\pm	R_s^\pm
		h^+h^-	$K\pi$	h^+h^-	$K\pi$	K^+K^-	$\pi^+\pi^-$	$K\pi$	$K\pi$
\mathcal{A}_{B^\pm}		0.7	0.7	0.7	0.7	–	–	–	–
\mathcal{A}_K		–	0.4	0.4	0.8	–	–	0.7	0.7
\mathcal{A}_π		0.3	–	–	0.3	–	–	0.6	0.3
Trigger		0.4	0.4	0.4	0.4	1.5	1.5	1.5	1.5
PID		0.6	0.6	0.6	0.6	1.2	1.2	1.2	1.2
Signal model		–	–	–	–	1.1	1.1	–	–
Bkgd. model		–	–	–	–	1.6	1.6	4.0	10.0
Charmless back.		–	–	–	–	1.0	1.0	1.0	1.0
Cross-feed		–	–	–	–	1.0	1.0	1.0	1.0
D vetoes		–	–	–	–	1.0	1.7	1.0	1.0
R_{CP+} approx.		–	–	–	–	1.0	1.0	–	–
Total		1.0	1.1	1.1	1.3	3.4	3.8	4.9	10.4