

	$\mathcal{A}_{CP}(\Lambda_b^0 \rightarrow \Lambda K^+ \pi^-)$	$\mathcal{A}_{CP}(\Lambda_b^0 \rightarrow \Lambda K^+ K^-)$
Control mode	66	57
PID asymmetry	20	–
Fit model	27	32
Fit bias	14	4
Efficiency uncertainty	80	28
Total	110	71