<table>
<thead>
<tr>
<th>Source of Uncertainty</th>
<th>$\mathcal{A}_{CP}(\Lambda_b^0 \rightarrow \Lambda K^+ \pi^-)$</th>
<th>$\mathcal{A}_{CP}(\Lambda_b^0 \rightarrow \Lambda K^+ K^-)$</th>
</tr>
</thead>
<tbody>
<tr>
<td>Control mode</td>
<td>66</td>
<td>57</td>
</tr>
<tr>
<td>PID asymmetry</td>
<td>20</td>
<td>–</td>
</tr>
<tr>
<td>Fit model</td>
<td>27</td>
<td>32</td>
</tr>
<tr>
<td>Fit bias</td>
<td>14</td>
<td>4</td>
</tr>
<tr>
<td>Efficiency uncertainty</td>
<td>80</td>
<td>28</td>
</tr>
<tr>
<td>Total</td>
<td>110</td>
<td>71</td>
</tr>
</tbody>
</table>